Kübler

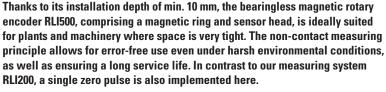
Bearingless encoders

Incremental, large hollow shaft zero pulse, magnetic

RLI500 (hollow shaft)

Push-pull / RS422





IP68 / IP69k protection, special encapsulation technology and tested resistance to cyclic humidity and damp heat offer the highest levels of reliability, even in exposed outdoor use.

This bearingless encoder can be mounted on shafts with a diameter up to \max . 350 mm.









High rotational speed

High protection level

Shock / vibration

Reverse polarity

Hard-wearing and robust

- · High shock and vibration resistance.
- Sturdy housing with IP67 protection. Option: special housing for maximum resistance against condensation (IP68 / IP69k, resistance to cyclic humidity acc. to EN 60068-3-38 as well as damp heat acc. to EN 60068-3-78).
- Non-contact measuring system, free from wear, ensures a long service life.

Fast start-up

- Function display via LED.
- Large mounting tolerance between magnetic band and sensor head.
- Requires very little installation space.
- · Slotted hole fixing ensures simple alignment.

Order code RLI500

$\begin{bmatrix} 8.\mathsf{RLI500} \\ \mathsf{Type} \end{bmatrix} . \begin{bmatrix} \mathsf{X} \\ \bullet \\ \bullet \end{bmatrix} 1 \begin{bmatrix} \mathsf{X} \\ \bullet \\ \bullet \end{bmatrix} . \begin{bmatrix} \mathsf{XXXXXX} \\ \bullet \end{bmatrix} . \begin{bmatrix} \mathsf{0700} \\ \bullet \\ \bullet \end{bmatrix}$

- a Magnetic ring mounting method
- 1 = Press fit 1)
- 2 = Hub screw
- 3 = Screwed flange 1)
- Model
- 1 = IP67, standard
- 2 = IP68 / IP69k and humidity tested acc. to EN 60068-3-38, EN 60068-3-78
- © Output circuit / Power supply
- 1 = RS422 / 4.8 ... 26 V DC
- 2 = Push-pull / 4.8 ... 30 V DC

- d Type of connection
- 1 = radial cable, 2 m [6.56'] PUR
- A = radial cable, special length PUR *)
- *) Available special lengths (connection type A): 3, 5, 8, 10, 15 m [9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.RLI500.21112A.4096.0700.0030 (for cable length 3 m)
- Pulses per revolution
 2048, 3200, 4096, 6400 (for hollow shaft ø 70 mm)
 (e.g.: 2048 pulses => 02048)



Optional on request

- other pulse rates
- other hollow shaft diameter (up to max. 350 mm)

Press fit



1) On request

With magnetic ring mounting method 1 or 3 on request.

Hub screw



Screwed flange





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Accessories / Display type 572		Order no.
Position display, 6-digit	with 4 fast switch outputs and serial interface	6.572.0116.D05
	with 4 fast switch outputs and serial interface and scalable analog output	6.572.0116.D95
Position display, 8-digit	with 4 fast switch outputs and serial interface	6.572.0118.D05
	with 4 fast switch outputs and serial interface and scalable analog output	6.572.0118.D95

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology

Technical data

Mechanical characteristi	ics	
Maximum speed		12000 min ⁻¹
Protection	model 1 model 2	IP67 acc. to EN 60529 IP68 / IP69k acc. to EN 60529, DIN 40050-9 and humidity tested acc. to EN 60068-3-38, EN 60068-3-78
Working temperature		-20°C +80°C [-4°F +176°F]
Shock resistance		5000 m/s ² , 1 ms
Vibration resistance		300 m/s ² , 10 2000 Hz
Pole gap		5 mm from pole to pole
Housing (sensor head)		aluminum
Cable		2 m [6.56'] long, PUR 8 x 0.14 mm ² [AWG 26], shielded, may be used in trailing cable installations
Status LED	green red	pulse index error; speed too high or magnetic fields too weak
CE compliant acc. to		EMC guideline 2014/30/EU RoHS guideline 2011/65/EU

Electrical char	acteristics	;					
Output circuit		RS422		Pusl	Push-pull		
Power supply		4.8 26 V DC		4.8	4.8 30 V DC		
Power consumption (no load)		typ. 25 mA max. 60 mA			typ. 25 mA max. 60 mA		
Permissible load/	channel	120 oh	120 ohm		+/- 20 mA		
Min. pulse edge interval		1 μs		1 µs	1 μs		
Signal level	HIGH LOW	min. 2.5 V max. 0.5 V		min. +V - 2.0 V max. 0.5 V			
Reference signal		fixed					
System accuracy		typ. 0.3° with shaft tolerance g6					
Pulse rate [ppr] 1)		2048	3200	4096	6400		
max. s	speed min ⁻¹	7300	4600	3600	2300		

Terminal assignment

Output circuit	Type of connection	Cable (isolate unused wires individually before initial start-up)									
1.2 1.4	Signal:	0 V	+V	Α	Ā	В	B	0	ō	Ŧ	
1, 2	1, A	Cable color:	WH	BN	GN	YE	GY	PK	BU	RD	shield ²⁾

Encoder power supply +V DC

+V: 0 V: Encoder power supply ground GND (0 V) A, \overline{A} : Incremental output channel A / sine signal B, B: Incremental output channel B / cosine signal

0, $\overline{0}$: Reference signal

Plug connector housing (shield)

With an input frequency of the evaluation unit of 250 kHz.
 Shield is attached to connector housing.



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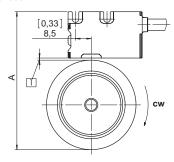
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Mounting orientation and permissible mounting tolerances

Distance:



1 Distance sensor head / magnetic ring: 0.1 ... 1.5 [0.004 ... 0.06] (1 [0.04] recommended)

Torsion







Tilting



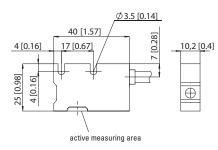
Impulsions par tour	Α
	for distance sensor head / magnetic ring = 1 mm [0.04]
	magnotio mig = 1 min [0.01]
2048, 3200, 4096, 6400	128.0 [5.04]

Warning: When mounting the sensor head, please ensure its correct orientation to the magnetic ring!

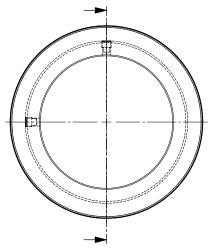
Dimensions

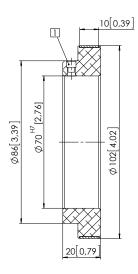
Dimensions in mm [inch]

Sensor head



Magnetic ring (hub screw) pulse rate 2048. 3200, 4096, 6400





1 M5 set screw M4